

1. Standard orientation

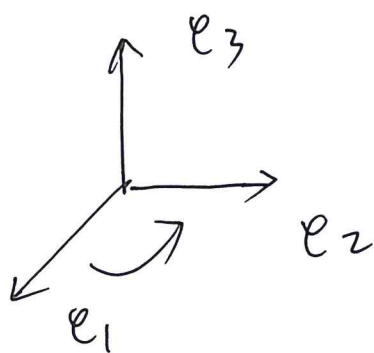
$$\vec{e}_i = (0, \dots, 0, \underset{\uparrow}{1}, 0, \dots, 0)$$

i-th coordinate

$\Rightarrow \{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\}$ forms a standard ordered basis

(corresponding to the standard orientation)

right hand rule.



$$(1) \{\vec{e}_1, \vec{e}_3, \vec{e}_2\} = -\{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$$

NS (not standard)

$$(2) \{\vec{e}_2, \vec{e}_3, \vec{e}_1\} = \{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$$

S

$$(3) \{\vec{e}_3, \vec{e}_1, \vec{e}_2\} = \{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$$

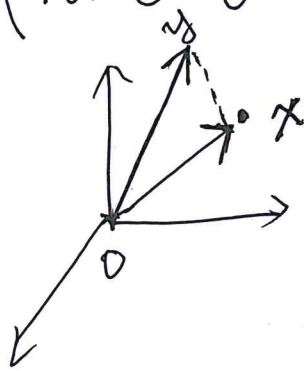
reason: change \vec{e}_3, \vec{e}_1 position $\rightarrow -\{\vec{e}_1, \vec{e}_3, \vec{e}_2\}$

change \vec{e}_3, \vec{e}_2 position $\rightarrow -(-\{\vec{e}_1, \vec{e}_2, \vec{e}_3\})$

$= \{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$ by basic property of

determinant.

2. the n -dimension vector forms a well corresponding relation with the point in n -dimension space. we can treat the point x in \mathbb{R}^n with the vector from 0 to x as the same guy.



So, for two points in \mathbb{R}^n , x and y , we know the

distance of them is $\|x - y\|$

when we set $x = (x_1, x_2, \dots, x_n)$

$y = (y_1, y_2, \dots, y_n)$

we ~~see~~ review the distance formula.

$$d(x, y) = \|x - y\| = \sqrt{(x_1 - y_1)^2 + \dots + (x_n - y_n)^2}$$

that is a natural generalization of the

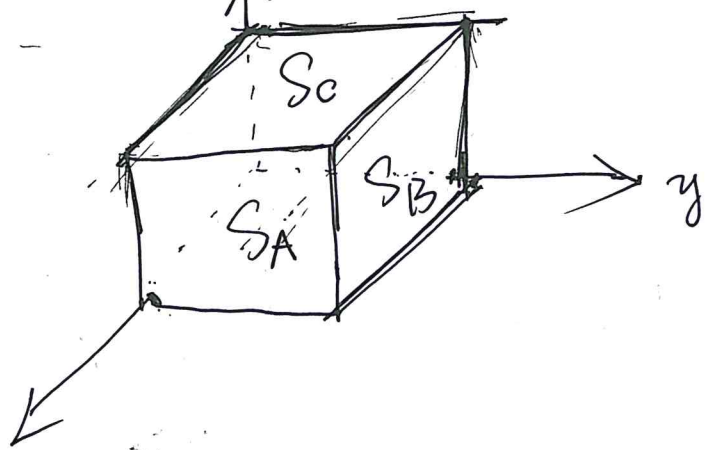
2-dim distance formula. to n-dim. $\frac{2}{7}$

the tool you have known is the so-called

Inner product!

3. Some exercise about drawing graph.

① $x=1, y=1, z=1$ respectively (first quadrant)



$x=1, S_A$

$y=1, S_B$

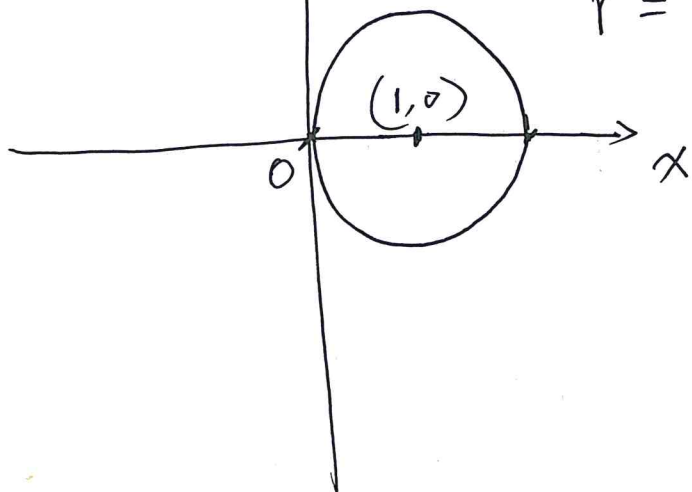
$z=1, S_C$

② $(x-1)^2 + y^2 = 1$

$n=2$

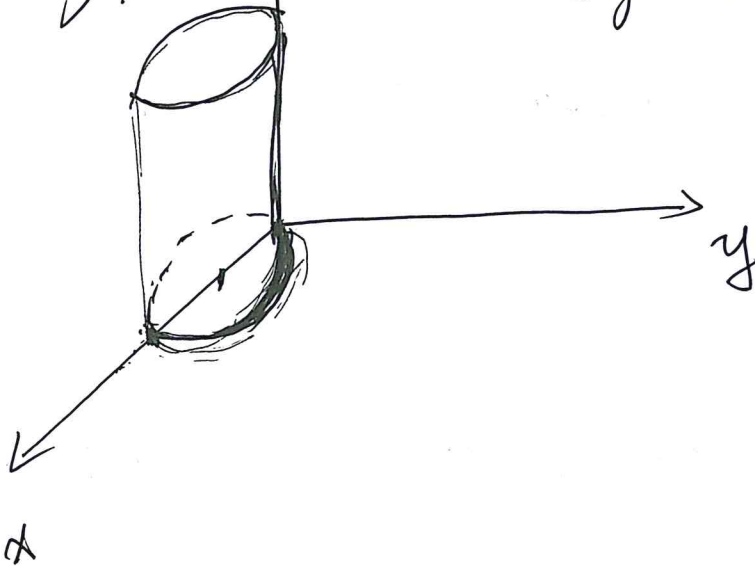
$O = (1, 0)$

$r=1$



$$n = 3.$$

Cylinder surface. \leq



③ find the centre and radii of

surface. $2x^2 + 2y^2 + 2z^2 + x + y + z = 9$

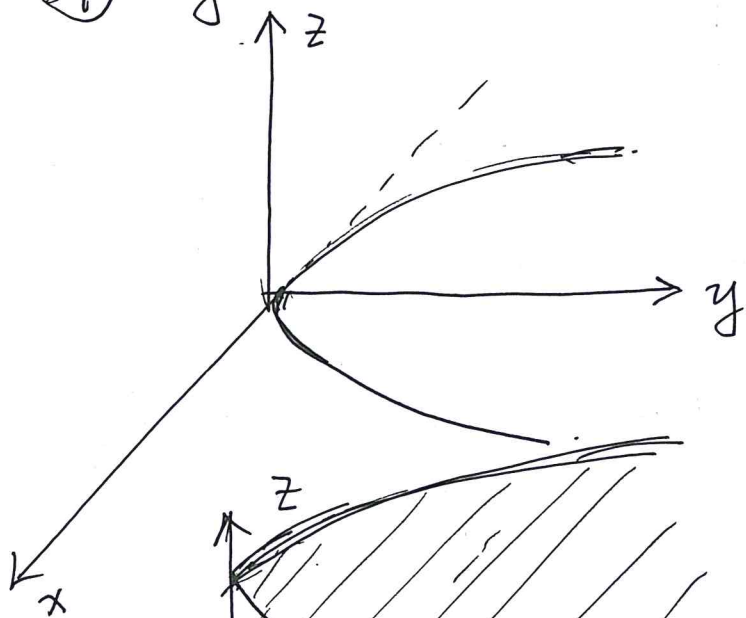
$$\Rightarrow 2\left(x^2 + \frac{1}{2}x\right) + 2\left(y^2 + \frac{1}{2}y\right) + 2\left(z^2 + \frac{1}{2}z\right) = 9$$

$$\Rightarrow 2\left(x + \frac{1}{4}\right)^2 + 2\left(y + \frac{1}{4}\right)^2 + 2\left(z + \frac{1}{4}\right)^2 = \frac{69}{8}$$

$$\Rightarrow \left(x + \frac{1}{4}\right)^2 + \left(y + \frac{1}{4}\right)^2 + \left(z + \frac{1}{4}\right)^2 = \left(\frac{\sqrt{69}}{4}\right)^2$$

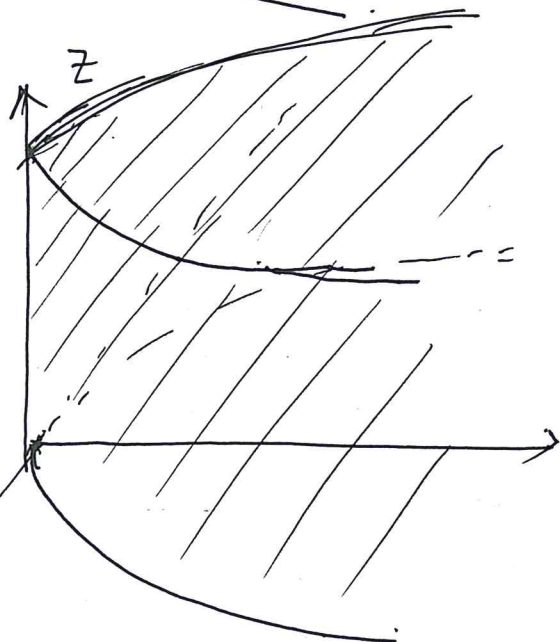
$$\text{C} : \left(-\frac{1}{4}, -\frac{1}{4}, -\frac{1}{4}\right), \quad r = \left(\frac{\sqrt{69}}{4}\right)^2$$

④ $y = x^2, z = 0.$



$y \geq x^2, z \geq 0.$

⑤

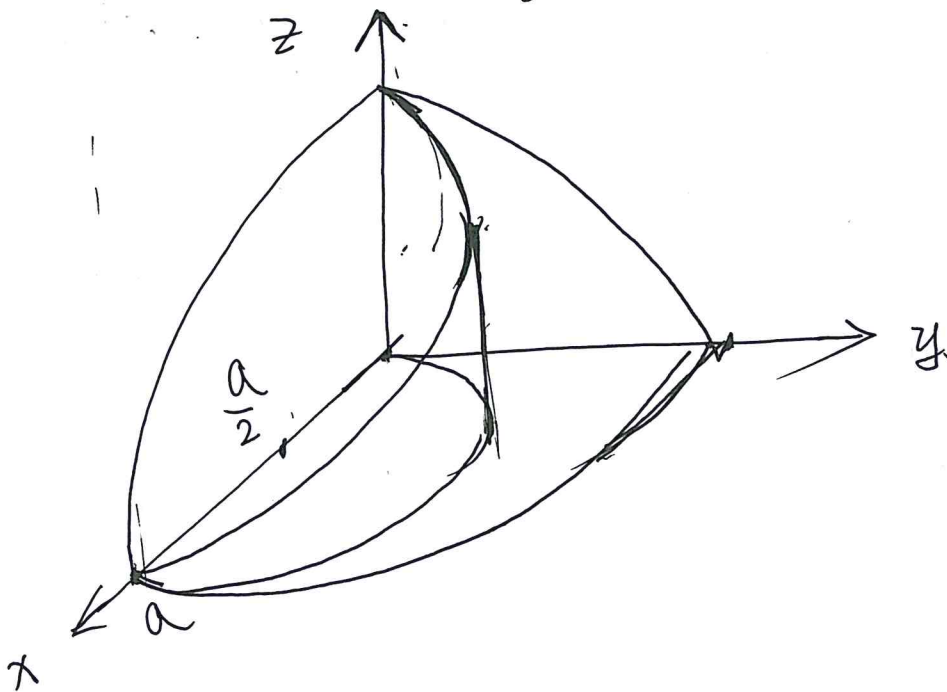


⑥

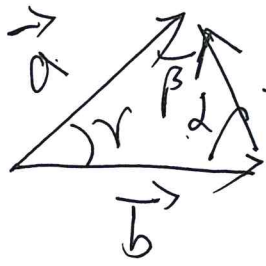
$x^2 + y^2 + z^2 = a^2$

$x^2 + y^2 = ax$

(first quadrant)



Complement for inner product and norm.



for a triangle. we'll ~~not~~
we have the sin law as

follows:

$$\frac{\|\vec{a}\|}{\sin \alpha} = \frac{\|\vec{b}\|}{\sin \beta} = \frac{\|\vec{a}-\vec{b}\|}{\sin \gamma}$$

$$(\alpha + \beta + \gamma = \pi)$$

$$\|x\| = \sqrt{\langle x, x \rangle}$$

norm: ~~the~~ three important property (or define method).

for Euclid norm especially: $x \in \mathbb{R}^n$

1. $\|x\| = 0 \Leftrightarrow x = 0$ $x = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$

2. $\|\lambda x\| = |\lambda| \cdot \|x\|$

3. $\|x+y\| \leq \|x\| + \|y\|$

~~Cauchy-Schwarz~~

a generalization of Cauchy-Schwarz. SA

inequality.

Holder inequality: $x = (x_1, x_2, \dots, x_n) \in \mathbb{R}^n$
 $y = (y_1, y_2, \dots, y_n) \in \mathbb{R}^n$

$$\underline{|\langle x, y \rangle| \leq \|x\|_p \cdot \|y\|_q.}$$

in which $\|x\|_p = (|x_1|^p + |x_2|^p + \dots + |x_n|^p)^{\frac{1}{p}}$

L^p -norm
for \mathbb{R}^n

$$\|y\|_q = (|y_1|^q + |y_2|^q + \dots + |y_n|^q)^{\frac{1}{q}}$$

~~and~~ $\langle x, y \rangle = x_1 y_1 + x_2 y_2 + \dots + x_n y_n$

$\frac{1}{p} + \frac{1}{q} = 1$, (p, q) called the Holder index

$(2, 2)$ corresponding Cauchy-Schwarz
 $(p \geq 1, q > 1)$ inequality.

